

Research Article

METHOD OF LOBACHEVSKI FOR SOLVING NON LINEAR ALGEBRAIC EQUATIONS WITH REAL COEFFICIENTS

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Abstract

The method of Lobachevski permits to determine both real and complex roots of nonlinear algebraic equations with real coefficients. Its advantages are that it is not necessary to priory search the intervals of appurtenance of the roots, it simultaneously gives all the roots, reducing the computational time when using other existing iterative methods, at last, its reliability during operational works is easy.

Keywords: Method of Lobachevski, Nonlinear algebraic equations with real coefficients, Squaring process, Intervals of location of the roots, Method of separation of the roots.

INTRODUCTION

Numerical treatments of empirical data usually lead to the resolution of nonlinear algebraic equations of the form

$$a_{n}x^{n} + a_{1}x^{n-1} + a_{2}x^{n-2} + \ldots + a_{n-1}x + a_{n} = 0,$$
(1)

where a_1 , i = 0, 1, 2, ..., n are real coefficients not all zeros. n - the degree of the equation.

Finding roots of such equations is one of the oldest problems of algebra. Algorithms for n = 1 and n = 2 have been elaborated. For $n \ge 3$ things begin to be complicated and only numerical methods can be very helpful. Between others, the methods of tangents and secants are the most encountered, (Burden and Faires, 2005; Melentev, 1962; Patel, 1994). Their common particularity is that they permit to find only one solution, meaning that the method must be repeated n times for the n roots. An important problem to be priory solved is the finding of the interval in which the root belongs and this is not always an easy task. This article exposes a method elaborated by Lobachevski in 1834, ameliorated by Graeffe in 1837 and extended for finding complex roots by Hanke in 1841, (Lobachevsky, 1948). Its actual form was given by Krylov. It is also called the method of separation of the roots. It offers many advantages, between others, the unnecessary finding of the intervals of appurtenance of roots, the simultaneously finding of all the roots, both real and complex ones and the shorter time of execution. Unfortunately, the method of Lobachevski seems to be neglected today. With the development of science, more complicated equations of form (1) are frequently encountered and their roots could only be found if using the method of Lobachevski, whence the importance of this paper. This work has five sections. The first one is this introduction to the problem to be solved. The second one exposes the principle of the methods of Lobachevski, one for real and distinct roots and another for both real and complex roots. Implementations of both methods are given in section three and the conclusion in section four. The references in alphabetic order are in section five.

PRINCIPLE OF THE METHOD

Consider a nonlinear algebraic equation of power n, $n \ge 3$: $f(x) = a_0 x^n + a_1 x^{n-1} + \dots + a_{n-1} x + a_n = 0$, (2)

with all nonzero real coefficients a_i , i = [0,n].

Let
$$x_1, x_2, ..., x_n$$
 be the n roots of (2) with:
 $|x_1| > |x_2| > \dots > |x_n|,$ (3)

where $|x_{i \in [1,n]}|$ is the module of x_i .

Equation (2) can be repeatedly transformed to new nonlinear algebraic equations such that their roots are the squares of the corresponding roots of the preceding equation. Thus, if 3 and 4 were roots of (2), then after the first transformation the roots of the new equation should be 3^2 and 4^2 and after k transformations, 3^m and 4^m with $m = 2^k$. The ratios of the roots of the initial and final equations are respectively $\frac{3}{4} = 0.75$ and $(3/4)^m$. For instance, if k = 5, m = 32, the second ratio should be 10^{-4} times smaller than the initial one. Thus, when k increases, the roots with a lowest module should be neglected compared to the one with a highest module. This is the principle of separation of the roots of an equation.

These transformations are made as follows.

Putting
$$x_i$$
, $i = 1, ..., n$, the roots of (2). We may also write:
 $f(x) = a_0 (x-x_1) (x-x_2) ... (x-x_n).$ (4)

From (2-3) we deduce f(-x):

$$\begin{aligned} f(-x) &= a_0 (-x - x_1) (-x - x_2) \dots (-x - x_n) \\ &= (-1)^n a_0 (x + x_1) (x + x_2) \dots (x + x_n). \end{aligned}$$

Multiplying (4) and (5) gives:

$$f(x)f(-x) = (-1)^n a_0^2 (x^2 - x_1^2) (x^2 - x_2^2) \dots (x^2 - x_n^2)$$
(6)

Putting $y = -x^2$ in (5) gives equation $\varphi(y)$ with:

$$\begin{split} \phi(\mathbf{y}) &= (-1)^n \, a_0^2(-\mathbf{y} - \mathbf{x}_1^2)(-\mathbf{y} - \mathbf{x}_2^2) \, \dots \, (-\mathbf{y} - \, \mathbf{x}_n^2) \\ &= a_0^2(\mathbf{y} + \mathbf{x}_1^2)(\mathbf{y} + \mathbf{x}_2^2) \, \dots \, (\mathbf{y} + \mathbf{x}_n^2) = \\ &= a_0^{(1)} \mathbf{y}^n + a_1^{(1)} \mathbf{y}^{n-1} + \, \dots \, + a_{n-1}^{(1)} \mathbf{y} + a_n^{(1)} = \mathbf{0}. \end{split}$$

The roots of (7) are $-x_1^2, -x_2^2, ..., -x_n^2$. (5) can be given the form:

$$f(-x) = a_0 x^n (-1)^n + a_1 x^{n-1} (-1)^{n-1} + \dots + a_n = = (-1)^n [a_0 x^n - a_1 x^{n-1} + \dots + a_n (-1)^n].$$
(8)

Taking (8) into consideration, (6) becomes:

$$\begin{split} f(x)f(-x) &= (-1)^n [a_0^2 x^{2n} - (a_1^2 - 2a_0a_2) x^{2n-2} + (a_2^2 - 2a_1a_3 + 2a_0a_4) x^{2n-4} + \ldots + (-1)^n a_n^2] \\ &= (-1)^n a_0^2 x^{2n} + (-1)^{n-1} (a_1^2 - 2a_0a_2) x^{2(n-1)} + \end{split}$$

$$+ (-1)^{n-2} (a_2^2 - 2a_1a_3 + 2a_0a_4)x^{2(n-2)} + \ldots + a_n^2 = 0.$$
(9)

Consequently, (7) becomes:

$$\begin{split} \phi(\mathbf{y}) &= a_0^2 \mathbf{y}^n + (a_1^2 - 2a_0 a_2) \mathbf{y}^{n-1} + (a_2^2 - 2a_1 a_3 + 2a_0 a_4) \mathbf{y}^{n-1} + \\ &+ \dots + a_n^2 = 0. \end{split} \tag{10}$$

(7) and (10) give the relationships between former and new coefficients:

(11) is the algorithm of computation of new coefficients $a_i^{(1)}$, i ϵ [0,n], after the first transformation. This algorithm could be generalized for any transformation. Thus, if we are at the k-th transformation, (11) take the next form:

Formulas (11a) tell us that the first and last coefficients of the transformed equation are just the squares of the corresponding ones from the preceding equation, i.e.

$$a_0^{(k)} = (a_0^{(k-1)})2$$
 and $a_n^{(k)} = (a_n^{(k-1)})^2$

and the second and before last coefficients are obtained subtracting from the squares of their corresponding coefficients the double products of their neighbouring coefficients, i.e.

 $a_1^{(k)} = (a_1^{(k-1)})^2 - 2 a_0^{(k-1)}a_2^{(k-1)}$, and $a_{n-1}^{(k)} = (a_{n-1}^{(k-1)})^2 - 2 a_{n-2}^{(k-1)}a_n^{(k-1)}$. The remaining coefficients are calculated subtracting from the squares of their corresponding coefficients the double products of their closest backward and forward coefficients and adding the double products of their own closest backward and forward coefficients, i.e.

$$a_{i}^{(k)} = (a_{i}^{(k-1)})^{2} - 2 a_{i-1}^{(k-1)} a_{i+1}^{(k-1)} + 2 a_{i-2}^{(k-1)} a_{i+2}^{(k-1)}, \ i = 2, ..., n-2.$$

These computations are repeated until all the double products are negligible as null, indicating that the precision has been reached. To proceed easily and faster while avoiding errors at the same time, computations should be done according to the scheme in Table 1. To reduce round-off errors, computations should be done with at least two more significant digits above the given precision.

Table 1. Intermediary computations of transformed coefficients

k	a ₀ ^(k)	a 1 ^(k)	a 2 ^(k)	 an ^(k)
0	a_0	a 1	a ₂	 an
	a_0^2	a_1^2	a_0^2	a_n^2
		a_1^2 - $2a_0a_2$	a_0^2 - 2a ₁ a ₃ +2a ₀ a ₄	
			$+2a_0a_4$	
1	$a_0^{(1)}$	$a_2^{(1)}$	$a_2^{(1)}$	$a_n^{(1)}$

When finding the roots of (2), the two more encountered cases are: **a**) all the roots are different real numbers; **b**) some of them are complex numbers. Let us examine each case.

a) All the roots are real and different.

At the k-th transformation, recall that $m=2^{k}$, the next system of relationships between the roots and coefficients of the given equation based on the theorem of Vieta can be established:

Based on (3) and on the fact that m is generally high, the following equalities can be deduced:

whence:

System (13b) gives at all the searched roots of (2) affected to power m. As m is an even number, $x_i = \pm \sqrt{x_i^m}$, i = 1, 2, ..., n. Substituting each value in (2) enables us to determine which sign should be considered.

b) Some roots are conjugate complex numbers

Let us divide both members of (2) by $a_0 \neq 0$. We obtain the next expression called the monic form of (2) as $b_0 = 1$:

$$x^{n} + b_{1}x^{n-1} + \dots + b_{n-1}x + b_{n} = 0.$$
(14)

If (14) has only a couple of conjugate complex roots, say x_2 and x_3 , so the remaining n-2 roots are real numbers which can be noted at the k-th transformation by $\beta_i = x_i^m$, i = 1, 2, ..., n-2, the two complex ones been x_2^m and x_2^m . So based on (13a), we may write the next relations:

$$b_1 = \beta_1, b_2 = \beta_1\beta_2, b_3 = \beta_1\beta_2\beta_3, ..., b_p = \beta_1\beta_2\beta_3..., \beta_p, p = n-2,$$
 (15a)

for the n-2 real roots and:

$$x_2^m = \rho_1(\cos\psi_1 + i\sin\psi_1), x_2^m = \rho_1(\cos\psi_1 - i\sin\psi_1),$$
 (15b)

for the two complex roots.

From (15a), we have:

$$\beta_1 = b_{1, \beta_2} = \frac{b_2}{b_1}, \beta_3 = \frac{b_3}{b_2}, \dots, \beta_p = \frac{b_p}{b_{p-1}},$$
 (16a)

Whence the real roots given by:

$$x_i = \pm \sqrt[m]{\beta_i}, i = 1, 2, ..., p.$$
 (16b)

Let us find the complex roots. As x_2 and x_3 are complex, it comes that the second real root, β_2 , corresponds to x_4^{m} . Thus based on (3), (12), and (15a), we may write:

Recalling that:

0

$$\begin{array}{ll} x_{2}^{m} + x_{3}^{m} = 2\rho_{1}cos\phi_{1} = 2 \ \rho_{1}cos\phi_{1}, & (a) \\ x_{2}^{m}x_{3}^{m} = \rho_{1}^{2} = r^{2m}, & (b) \end{array}$$
(18)

Taking into account (17) and (18), (15a) becomes:

$$b_{1} = \beta_{1}, b_{2} = x_{1}^{m} x_{2}^{m} + x_{1}^{m} x_{3}^{m} = \beta_{1} 2 \rho_{1} \cos \phi_{1}, b_{3} = x_{1}^{m} x_{2}^{m} x_{1}^{m} = \beta_{1} \rho_{1}^{2}, b_{4} = x_{1}^{m} x_{2}^{m} x_{1}^{m} x_{4}^{m} = \beta_{1} \rho_{1}^{2} \beta_{2},$$
(19)

From the first and third equations of system (19), we have the module r of the complex roots:

$$\frac{b_3}{b_1} = \rho_1^2, r = \sqrt[m]{\rho_1^2}.$$
 (20)

From the first and second equations of system (19), we have:

$$\frac{b_3}{b_1} = 2 \rho_1 \cos \varphi_1 = 2 \rho_1 \cos \psi$$
(21)

Recalling that:

$$b_1 = -(x_1^{m} + 2r_1 \cos\varphi_1 + x_4^{m} + \dots + x_n^{m}), \qquad (22)$$

and considering (21), the argument of the complex roots is easily found.

Suppose that (2) has more than one couple of conjugate complex roots, say two such roots. In this case, we have two conjugate complex numbers, i.e. four complex roots. We must form a system of two equations (similar to (22)) to solve for the arguments of the complex roots. Their modules are obtained using formula similar to (20).

To obtain the system of the two equations for the arguments, we proceed dividing both members of (2) by $a_0x^n \neq 0$:

$$\frac{1}{a_0} + \frac{a_{n-1}}{a_0} \cdot \frac{1}{x} + \frac{a_{n-2}}{a_0} \cdot \frac{1}{x^2} + \dots + \frac{a_1}{a_0} \cdot \frac{1}{x^{n-1}} + \frac{1}{x^n} = 0.$$
 (23)

Putting $\frac{1}{x} = y$, we have:

$$y^{n} + \frac{a_{1}}{a_{0}} y^{n-1} + \frac{a_{2}}{a_{0}} y^{n-2} + \dots + \frac{a_{n-1}}{a_{0}} y + \frac{1}{a_{0}} = 0.$$
 (24)

Based on the formula of Vieta we have:

$$\frac{a_1}{a_0} = -\left(\frac{1}{\beta_1} + \frac{1}{\beta_2} + \dots + \frac{1}{\beta_j} + \frac{1}{r_{1(\cos\varphi_1 + i\sin\varphi_1)}} + \frac{1}{r_{1(\cos\varphi_1 - i\sin\varphi_1)}} + \frac{1}{r_{2(\cos\varphi_2 - i\sin\varphi_2)}}\right), j = 1, 2, \dots, n - 4$$
(25)

Recalling that:

$$\frac{1}{r\left(\cos\varphi+i\sin\varphi\right)} + \frac{1}{r\left(\cos\varphi-i\sin\varphi\right)} = \frac{2\cos\varphi}{r}.$$
 (26)

and based on (26), expression (25) becomes:

$$\frac{a_1}{a_0} = -\left(\frac{1}{\beta_1} + \frac{1}{\beta_2} + \dots + \frac{1}{\beta_j} + \frac{2\cos\varphi_1}{r_1} + \frac{2\cos\varphi_2}{r_2}\right)$$
(27)

Thus, the system equations to solve for the arguments are:

$$a_{n-1} = -(\beta_1 + \beta_2 + \dots + \beta_j + 2r_1 \cos\varphi_1 + 2r_2 \cos\varphi_2),$$

$$a_1 = -(\beta_1 + \beta_2 + \dots + \beta_j + 2r_1 \cos\varphi_1 + 2r_2 \cos\varphi_2),$$
(23)

$$\frac{a_1}{a_0} = -\left(\frac{1}{\beta_1} + \frac{1}{\beta_2} + \dots + \frac{1}{\beta_j} + \frac{2\cos\varphi_1}{r_1} + \frac{2\cos\varphi_2}{r_2}\right).$$
 (28)

Knowing the cosines and modules of the two couples of conjugate complex roots, it becomes easier to find these roots solving two quadratic equations of the form $x^2 - 2r\cos\varphi x + r^2 = 0$ by the quadratic formulas.

IMPLEMENTATION OF THE METHODS

These methods are implemented on equations obtained during practical works on the numerical methods frequently used in weather forecast at the Hydrometeorological Institute of Leningrad, State Hydrometeorological University of Saint Petersburg, today, Russia.

Case of real and distinct roots

Let us solve the following equation:

$$f(x) = 1.23x^5 - 2.52x^4 - 16.1x^3 + 17.3x^2 + 29.4x - 1.34 = 0 \quad (29)$$

The computations in Table 2 are stopped for k = 6, i.e. $m = 2^{k} = 2^{6} = 64$ as at this stage, all the double products, $2a_{i-1}a_{i+1}$ and $2a_{i-2}a_{i+2}$, are at most 10^{-4} times lower than the main terms, a_{i}^{2} . Using Table 2, (13b) gives:

k	\mathbf{a}_0	a ₁	a ₂	a 3	84	a 5
0	1.23	-2.52	-16.1	17.3	29.4	-1.34
	1.5129	6.3504	2.5921 10 ²	2.9929 10 ²	8.6436 10 ²	1.7956
		+39.6060	$+0.8719 \ 10^2$	$+9.4668$ 10^{2}	$+0.4633$ 10^{2}	
			$+0.7232 10^2$	$+0.0675$ 10^{2}		
1	1.5129	$0.4596 10^2$	4.1873 10 ²	$1.2527 10^3$	9.1072 10^2	1.7956
	22884	$2.1120 10^3$	1.7533 10 ⁵	1.5693 10 ⁶	8.2942 10 ⁵	3.2242
		$-1.2670 \ 10^3$	-1.1514 10 ⁵	-0.7627 10^{6}	-0.0450 10 ⁵	
			+0.0276 10 ⁵	$+0.0002$ 10^{6}		
2	2.2880	$0.8450 \ 10^3$	$0.6295 10^5$	$0.8068 10^6$	8.2492 10 ⁵	3.2242
	5.2391	7.1404 10 ⁵	3.9622 10 ⁹	6.5092 10 ¹¹	6.8049 10 ¹¹	10.3955
		$-2.8815 \ 10^{5}$	-1.3635 10 ⁹	⁻ 1.0385 10 ¹¹	$0.0000 10^{11}$	
			$0.0040 10^9$	$+0.0000 10^{11}$		
3	5.2391	4.2589 10 ⁵	2.6027 10 ⁹	5.4707 10 ¹¹	6.8049 10 ¹¹	10.3955
	$2.7448 \ 10^1$	1.8138 10 ¹¹	6.7740 10 ¹⁸	2.9930 10 ²³	4.6307 10 ²³	1.0807 102
		-0.2727 10 ¹¹	-0.4660 10 ¹⁸	$-0.0354 10^{23}$	$-0.0000 \ 10^{23}$	
			$+0.0000 \ 10^{18}$	$+0.0000 10^{23}$		
4	$2.7448 \ 10^1$	1.5411 10 ¹¹	6.3080 10 ¹⁸	2.9576 10 ²³	4.6307 10 ²³	1.0807 102
	$7.5340 \ 10^2$	2.3750 10 ²²	3.9791 10 ³⁷	8.7474 10 ⁴⁶	2.1443 10 ⁴⁷	1.1678 104
		-00346 10 ²²	$-0.0091 10^{37}$	$-0.0001 10^{46}$	$-0.0000 \ 10^{47}$	
			$+0.0000 \ 10^{37}$	$+0.0000 10^{46}$	-0.0000 10 ⁴⁷	
5	$7.5340 \ 10^2$	2.3404 10 ²²	$3.9700 10^{37}$	8.7473 10 ⁴⁶	2.1443 10 ⁴⁷	1.1678 104
	$0.5676 \ 10^{6}$	5.4773 10 ⁴⁴	1.5761 10 ⁷⁵	$7.6515 10^{93}$	4.5980 10 ⁹⁴	1.3638 108
		$-0.0001 \ 10^{44}$	$-0.0000 10^{75}$	$-0.0000 10^{93}$	-0.0000 10 ⁹⁴	
			$+0.0000 \ 10^{75}$	$+0.0000 \ 10^{93}$		
6	$0.5676 \ 10^6$	5.4774 10 ⁴⁴	1.5761 10 ⁷⁵	7.6715 10 ⁹³	4.5980 10 ⁹⁴	1.3638 108

Table 2. Table of intermediary computations of the roots of (3-1)

 Table 3. Table of intermediary computations of the roots of (3-2)

k	a ₀ ^(k)	$a_1^{(k)}$	$a_2^{(k)}$	<i>a</i> ^(<i>k</i>)	$a_4^{(k)}$
0	1	0.68342	1.95562	0.37654	1.79420
	1	0.46706	3.82445	0.14178	3.21915
		- 3.91124	- 0.51467	- 7.01755	
			+3.58840		
1	1	- 3.44418	6.89818	- 6.87577	3.21915
	1	11.86238	47.58489	47.27621	10.36293
		- 13.79636	- 47.36278	- 44.41255	
			6.43830		
2	1	- 1.93398	6.66041	2.86366	10.36293
	1	3.74028	44.36106	8.20055	107.39032
		- 13.32082	11.07652	- 138.04273	
			20.72586		
3	1	- 9.58054	76.16344	- 129.84218	107.39032
	1	91.78675	$5.80087 \cdot 10^{3}$	$1.68590 \cdot 10^4$	$1.15327 \cdot 10^4$
		- 152.32688	$-2.4879 \cdot 10^{3}$	$-1.6358 \cdot 10^4$	
	_	<pre>c o # 4 o 4 o 1</pre>	$0.21478 \cdot 10^3$	0.0.000000000	
4	1	-6.05401·10 ¹	3.52773·10 ³	0.05006·10 ⁴	1.15327·10 ⁴
	1	$3.66511 \cdot 10^3$	$1.24449 \cdot 10^{7}$	$2.50600 \cdot 10^{5}$	$1.33003 \cdot 10^8$
		$-7.05546 \cdot 10^3$	$6.06127 \cdot 10^4$	$-8.1368 \cdot 10^7$	
-	1	2 20025 103	$2.30654 \cdot 10^4$	0.1110.107	1 22002 108
5	1	$-3.39035 \cdot 10^3$	1.25286.107	-8.1118·10 ⁷	$1.33003 \cdot 10^8$
	1	$11.49447 \cdot 10^{6}$	1.56966·10 ¹⁴	$6.58011 \cdot 10^{15}$	$1.76898 \cdot 10^{16}$
		$-2.50572 \cdot 10^7$	$5.50036 \cdot 10^{11}$	$-3.3327 \cdot 10^{15}$	
(1	1 25(27 107	$2.66006 \cdot 10^8$	2 24742 1015	1 7(000 100
6	1	$-1.35627 \cdot 10^7$	$1.56911 \cdot 10^{14}$	3.24743·10 ¹⁵	$1.76898 \cdot 10^{16}$
	1	$1.83947 \cdot 10^{14}$	$2.46211 \cdot 10^{28}$	$1.05458 \cdot 10^{31}$	$3.12929 \cdot 10^{32}$
		$-3.13822 \cdot 10^{14}$	$8.80878 \cdot 10^{22}$	$-5.5514 \cdot 10^{30}$	
7	1	1 20075.1014	$3.53796 \cdot 10^{16}$	0.40044.1031	2 12020-1032
7	1	$-1.29875 \cdot 10^{14}$	$2.46211 \cdot 10^{28}$	$0.49944 \cdot 10^{31}$	$3.12929 \cdot 10^{32}$

$$\begin{aligned} x_1^{64} &\approx \frac{5.4774 \cdot 10^{44}}{0.5676 \cdot 10^6}, \ x_2^{64} &\approx \frac{1.5761 \cdot 10^{75}}{5.4774 \cdot 10^{44}}, \ x_3^{64} &\approx \frac{7.6514 \cdot 10^{93}}{1.5761 \cdot 10^{75}} \\ x_4^{64} &\approx \frac{4.5980 \cdot 10^{94}}{7.5614 \cdot 10^{93}}, \ x_5^{64} &\approx \frac{1.3638 \cdot 10^8}{4.5980 \cdot 10^{94}} \end{aligned}$$

whence:

 $x_1 \!\!\approx \!\!\pm 4.0657; x_2 \!\!\approx \!\!\pm 2.9917; x_3 \!\!\approx \!\!\pm 1.9587; \ x_4 \!\!\approx \!\!\pm 1.0284; x_5 \!\!\approx \!\!\pm 0.0445.$

By substitution in the initial equation we have the searched roots:

 $x_1 \approx$ 4.0657; $x_2 \approx$ - 2.9917; $x_3 \approx$ 1.9587; $x_4 \approx$ - 1.0284; $x_5 \approx$ 0.0445.

Case of real distinct and complex roots

Let us solve the following equation in its monic form:

 $x^{4} + 0.68342 x^{3} + 1.95562 x^{2} + 0.37654 x + 1.79420 = 0$ (30)

This equation of degree four must have four roots. Intermediary computations are presented in Table 3.

The variations of coefficients $a_1^{(k)}$ and $a_3^{(k)}$ in Table 3 are not homogeneous as the double products of the corresponding coefficients remain of the same order as the square of the main

coefficients. Moreover their signs are not constant when passing from iteration to another. As two columns are concerned, the initial equation has two couples of conjugate complex roots, so all the roots are complex. At k = 7, $m = 2^7 = 128$, these double products do not more affect the square of the main coefficients in column $a_2^{(k)}$. This indicates that we can stop the squaring process.

Formula (20) permits us to find the modules of the complex roots:

$$(r_1^2)^{128} = \frac{2.46211 \cdot 10^{28}}{1}, r_1 = 1.29093,$$

 $(r_2^2)^{128} = \frac{3.12929 \cdot 10^{32}}{2.46211 \cdot 10^{28}}, r_2 = 1.03760.$

From (28) we have the system of two equations to be solved for the cosines of the arguments:

 $0.68342 = -(2.58186\cos\varphi_1 + 2.07520\cos\varphi_2),$

$$\frac{0.37654}{1.79420} = -\left(\frac{2\cos\varphi_1}{1.29093} + \frac{2\cos\varphi_2}{1.03760}\right).$$

We have: $\cos \varphi_1 = -0.50063$ and $\cos \varphi_2 = 0.29354$.

Letting $x_{1,2}$ and $x_{3,4}$ the two couples of conjugate complex roots and recalling that:

 $x_1 + x_2 = 2 \cos \varphi_1 = -1.29259, x_1 x_2 = r_1^2 = 1.66644, x_3 + x_4 = 2 \cos \varphi_2 = 0.60917, x_3 x_4 = r_2^2 = 1.07667,$

the initial equation can be put into the product of two quadratic factors:

 $x^{4} + 0.68342 x^{3} + 1.95562 x^{2} + 0.37654 x + 1.79420 =$ $(x^{2} + 1.29259x + 1.66644) (x^{2} - 0.60917x + 1.07667) = 0,$

and solving each one by quadratic formulas gives the searched complex roots.

Conclusion

It is obvious that the method of Lobachevski is easily applicable when searching roots of nonlinear algebraic equations. No powerful computer is needed and a pocket simple scientific calculator can be used. This method gives all the roots at once, compare to other frequently encountered iterative methods, without wasting time searching their intervals of appurtenance. Thus, the method of Lobachevski should be widely recommended for operational works.

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